

Unit - II

Linear Transformations

Sec: 6.1 The Algebra of linear transformations

Defn: A non-empty set R is said to be associative ring if in R there are defined two operations denoted by "+" and "." respectively such that for all a, b, c in R .

- 1) $a+b \in R$
- 2) $a+b = b+a$
- 3) $a+(b+c) = (a+b)+c$
- 4) there is an element $0 \in R$ such that $0+a = a+0 = a$.
- 5) $\exists -a \in R$ such that $-a+a = 0 = a+(-a)$
- 6) $a \cdot b \in R$
- 7) $a \cdot (b \cdot c) = (a \cdot b) \cdot c$
- 8) $a \cdot (b+c) = a \cdot b + a \cdot c$ and $(a+b) \cdot c = a \cdot c + b \cdot c$

Defn: An associative ring A is said to be an algebra over F if A is a vector space over F such that for all $a, b \in A$ and $\alpha \in F$. $\alpha(ab) = (\alpha a)b = a(\alpha b)$.

Defn: The element of $A(V)$ is called the linear transformation on V over F . Hence $A(V)$ is called algebra of linear transformation on V .

Lemma 6.1.1

[Analog of Cayley's Theorem for algebra]

If A is an algebra, with unit element, over F , then A is isomorphic to a subalgebra of $A(V)$ for some vector space V over F .

Proof:

Since A is an algebra over F , A is a vector space over F .

We shall use $V = A$

If $a \in A$ define $T_a: A \rightarrow A$

ie) $T_a: V \rightarrow V$ by $vT_a = va$ for every $v \in A$.

To prove: T_a is a linear transformation on V .

ie) ~~To prove~~: $T_a \in A(V)$.

Let $v_1, v_2 \in V$ and $\alpha \in F$.

$$\begin{aligned} \text{Then } (v_1 + v_2)T_a &= (v_1 + v_2)a \\ &= v_1a + v_2a \\ &= v_1T_a + v_2T_a \end{aligned}$$

$$\begin{aligned} (\alpha v_1)T_a &= (\alpha v_1)a \\ &= \alpha(v_1a) \\ &= \alpha(v_1T_a) \end{aligned}$$

$\therefore T_a$ is a linear transformation on V .

$\therefore T_a \in A(V)$.

Define $\psi: A \rightarrow A(V)$ by $a\psi = T_a \forall a \in A$.

To prove: ψ is an isomorphism from A into $A(V)$.

Let $a, b \in A$, $\alpha, \beta \in F$ and $T_a, T_b \in A(V)$.

To prove: $(\alpha a + \beta b)\psi = \alpha(a\psi) + \beta(b\psi)$

For any $v \in V$.

$$v(T_{\alpha a + \beta b}) = v(\alpha a + \beta b)$$

$$= v(\alpha a) + v(\beta b)$$

$$= \alpha(va) + \beta(vb)$$

$$= \alpha(vT_a) + \beta(vT_b)$$

$$= v(\alpha T_a) + v(\beta T_b)$$

$= v(\alpha T_a + \beta T_b)$ is true for all $v \in V$

$$T_{\alpha a + \beta b} = \alpha T_a + \beta T_b$$

Now $(\alpha a + \beta b)\psi = T_{\alpha a + \beta b}$.

$$\begin{aligned}
 T(a+b) &= \alpha T_a + \beta T_b \\
 &= \alpha(a\psi) + \beta(b\psi) \\
 (\alpha + \beta)\psi &= \alpha(a\psi) + \beta(b\psi)
 \end{aligned}$$

$\therefore \psi$ is a vector space homomorphism of A into $A(V)$.

claim: $T_{ab} = T_a \cdot T_b \quad \forall T_a, T_b \in A(V)$

Let $v \in V$.

$$\begin{aligned}
 v(T_{ab}) &= v(ab) \\
 &= (va)b \\
 &= (vT_a)T_b \\
 &= v(T_a T_b)
 \end{aligned}$$

ie) $v(T_{ab}) = v(T_a \cdot T_b)$ is true for all $v \in V$.

$$\Rightarrow T_{ab} = T_a \cdot T_b$$

$$\begin{aligned}
 \text{Now } (ab)\psi &= T_{ab} \\
 &= T_a T_b
 \end{aligned}$$

$$(ab)\psi = a\psi \cdot b\psi$$

ψ is a ~~dis~~ a ring homomorphism of A .

To prove: ψ is 1-1

ie) To prove: $\ker \psi = \{0\}$.

Let $a \in \ker \psi$.

Then $a\psi = 0$.

$$\Rightarrow T_a = 0$$

$$\Rightarrow \forall T_a = 0 \quad \forall v \in V \in A$$

$$\Rightarrow e T_a = 0 \quad [\because A \text{ is an algebra with unit element } e]$$

$$\Rightarrow e \cdot a = 0$$

Hence ψ is an isomorphism from A into $A(V)$.

$\therefore A$ is isomorphic to the image of A under ψ .

ie) Range of ψ which is subalgebra of $A(V)$.

Note: Let A be an algebra with unit element e over F and let $P(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2 + \dots + \alpha_n x^n$ be a polynomial in $F[x]$.

Lemma: 6.1.2

Let A be an algebra, with unit element, over F , and suppose that A is of dimension m over F . Then every element in A satisfies some nontrivial polynomial in $F[x]$ of degree at most m .

Proof:

Let A be an algebra over F with unit element e and $\dim_F A = m$.

Let $a \in A$.

Consider the $m+1$ elements e, a, a^2, \dots, a^m in A .

Since $\dim_F A = m$, these $(m+1)$ elements are linearly dependent over F [By Lemma: 4.2.4]

ie) \exists some elements $\alpha_0, \alpha_1, \dots, \alpha_m$ not all zero such that $\alpha_0 e + \alpha_1 a + \dots + \alpha_m a^m = 0$.

$\Rightarrow a$ satisfies a nontrivial polynomial.

$P(x) = \alpha_0 + \alpha_1 x + \dots + \alpha_m x^m$ of degree at most m .

Thus every element in A satisfies some nontrivial polynomial in $F[x]$ of degree at most m .

Theorem: 6.1.1

If V is an n -dimensional vector space over F , then given by any element T in $A(V)$, there exist a nontrivial polynomial $q(x) \in F[x]$ of degree at most n , such that $q(T) = 0$.

Proof:

Let V be an n -dimensional vector space over F .

Then $A(V)$ is an algebra over F with unit element and $\dim_F A(V) = n^2$. [∵ $\dim_F V = n$ then $\dim_F \text{Hom}(V, V) = n^2$]

By the above Lemma, any element in $A(V)$ satisfies a nontrivial polynomial $q(x)$ in $F[x]$ of degree at most n^2 such that $q(T) = 0$.

Defn: If V is finite dimensional over F and $T \in A(V)$. Then a nontrivial polynomial $p(x)$ in $F[x]$ of smallest positive degree satisfied by T is called minimal polynomial of T over F .

Note: If $p(x)$ is a minimal polynomial of T over F and $q(x) \in F[x]$ is satisfied by T then $p(x) \mid q(x)$.

Defn: (i) An element $T \in A(V)$ is called right invertible if \exists an element $S \in A(V)$ such that $TS = 1$.

(ii) An element $T \in A(V)$ is called left invertible if \exists an element $U \in A(V)$ such that $UT = 1$.

Remark: If T is both right and left invertible and if $TS = UT = 1$ then $S = U$ and S is unique.

Defn: An element $T \in A(V)$ is called invertible or regular if there exist an element $S \in A(V)$ such that $ST = TS = 1$.
ie) It is both left and right invertible.

Here we write S as T^{-1} .

Defn: An element $T \in A(V)$ is called singular if it is not regular.

~~Example 1~~ An element T in $A(V)$ is invertible or regular if it is not which is not regular is called singular. An element in $A(V)$ is right invertible but is not invertible.

Let F be the field of real numbers and $V = F[x]$ the set of all polynomials in x over F .

Define S on V by $q(x) \cdot S = \frac{d}{dx} q(x)$.

Then $S \in A(V)$.

Define T on V by $q(x) T = \int q(x) dx$.

Then $ST \neq 1$, Then $TS = 1$.

$$\begin{aligned} \text{For } q(x) T S &= (q(x) T) S \\ &= \left(\int q(x) dx \right) S \\ &= \frac{d}{dx} \int q(x) dx = q(x). \end{aligned}$$

$$TS = 1.$$

$\therefore T$ is right invertible.

Now,

$$q(x) S T = (q(x) S) T$$

$$= \left(\frac{d}{dx} q(x) \right) T$$

$$= \int \frac{d}{dx} q(x) dx$$

$$= (q(x))'$$

$$= q(x) - q(1) \neq q(x)$$

$$q(x) S T \neq q(x)$$

$$\Rightarrow ST \neq 1$$

$\Rightarrow T$ is not left invertible.

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~~Lemma 6.1.2~~ Theorem: 6.1.2

If V is finite-dimensional over F , then $T \in A(V)$ is invertible iff the constant term of the minimal polynomial T is not 0.

Proof:

Let $P(x) = a_0 + a_1 x + \dots + a_k x^k$ where $a_k \neq 0$.
be the minimal polynomial for T in $F[x]$.

Assume that $a_0 \neq 0$.

To prove: $T \in A(V)$ is invertible.

$$\text{Since } P(T) = 0 \Rightarrow a_0 + a_1 T + \dots + a_k T^k = 0.$$

$$\Rightarrow a_1 T + a_2 T^2 + \dots + a_k T^k = -a_0.$$

$$\div (-a_0) \Rightarrow \frac{-1}{a_0} (a_1 T + a_2 T^2 + \dots + a_k T^k) = 1$$

$$\text{(ie) } T \left[\frac{-1}{a_0} (a_1 + a_2 T + \dots + a_k T^{k-1}) \right] = 1.$$

$$\text{Take } S = \frac{-1}{a_0} (a_1 + a_2 T + \dots + a_k T^{k-1})$$

$$\therefore ST = TS = 1.$$

Hence T is invertible.

Conversely, Assume T is invertible.

To prove: $a_0 \neq 0$.

$$\text{Suppose } a_0 = 0.$$
$$P(T) = 0 \Rightarrow a_1 T + a_2 T^2 + \dots + a_k T^k = 0.$$

$$\Rightarrow T(a_1 + a_2 T + \dots + a_k T^{k-1}) = 0.$$

Since T is invertible $\Rightarrow T^{-1}$ exists.

$$\text{Then } T^{-1} T (a_1 + a_2 T + \dots + a_k T^{k-1}) = T^{-1} \cdot 0$$

$$a_1 + a_2 T + \dots + a_k T^{k-1} = 0.$$

Which is a contradiction to $P(x)$ is the minimal polynomial for T over F .

Corollary: 1
 If V is finite-dimensional over F and if $T \in A(V)$ is invertible, then T^{-1} is a polynomial expression in T over F .

Proof:

Let $P(x) = a_0 + a_1x + \dots + a_kx^k$ where $a_k \neq 0$ be the minimal polynomial for T over F .

Suppose $T \in A(V)$ is invertible.

Then by the above Theorem, $a_0 \neq 0$.

$$\text{Now, } P(T) = 0 \Rightarrow a_0 + a_1T + \dots + a_kT^k = 0$$

$$\Rightarrow a_1T + a_2T^2 + \dots + a_kT^k = -a_0$$

$$\Rightarrow \frac{-1}{a_0} (a_1 + a_2T + \dots + a_kT^{k-1}) T = 1.$$

$$\text{(ie) } T \left[\frac{-1}{a_0} (a_1 + a_2T + \dots + a_kT^{k-1}) \right] = 1.$$

$$\text{Take } S = \frac{-1}{a_0} (a_1 + a_2T + \dots + a_kT^{k-1})$$

$$\therefore ST = TS = 1.$$

$$\Rightarrow S \text{ is the inverse of } T \text{ (ie) } S = T^{-1}$$

$$\therefore T^{-1} = \frac{-1}{a_0} (a_1 + a_2T + \dots + a_kT^{k-1})$$

$\Rightarrow T^{-1}$ is a polynomial expression in T over F .

Corollary: 2

If V is finite-dimensional over F and if $T \in A(V)$ is singular, then there exists an $S \neq 0$ in $A(V)$ such that $ST = TS = 0$.

Proof:

Let $P(x) = a_0 + a_1x + \dots + a_kx^k$ where $a_k \neq 0$ be the minimal polynomial for T over F .

Since $T \in A(V)$ is singular,

By Theorem: 6.1.2, the constant term of

polynomial d_0 is zero.

$$\therefore p(x) = d_1 x + \dots + d_k T^k$$

$$\text{Then } p(T) = 0 \Rightarrow d_1 T + d_2 T^2 + \dots + d_k T^k = 0$$

$$(d_1 + d_2 T + \dots + d_k T^{k-1}) T = 0$$

$$\text{ie) } T(d_1 + d_2 T + \dots + d_k T^{k-1}) = 0$$

$$\text{Take } S = d_1 + d_2 T + \dots + d_k T^{k-1}$$

$$\text{Then } ST = TS = 0 \text{ and } S \in A(V)$$

claim: $S \neq 0$.

Suppose $S = 0$.

$$\Rightarrow d_1 + d_2 T + \dots + d_k T^{k-1} = 0$$

$\Rightarrow T$ satisfies a polynomial of degree $k-1$

which is a contradiction to $p(x)$ is a minimal polynomial for T .

$$\therefore S \neq 0$$

Hence there exist $S \neq 0$ in $A(V)$ such that

$$ST = TS = 0$$

Corollary: 3

If V is finite-dimensional over F and if $T \in A(V)$ is right invertible. Then it is invertible.

Proof:

Let $T \in A(V)$ is right invertible.

Then there exist $U \in A(V)$ such that $TU = 1$.

To prove: T is invertible.

Suppose T is not invertible.

ie) T is singular. Then by above Corollary,

there exists $S \neq 0$ in $A(V)$ such that $ST = TS = 0$.

$$\text{Now, } S = S \cdot 1 = ST = TS$$

$$= S(TU) = (ST)U$$

$$= 0 \cdot v = 0.$$

$$\Rightarrow S = 0.$$

Which is a contradiction to $S \neq 0$.

$\therefore T$ is invertible.

Theorem: 6.1.3

If V is finite dimensional over F , then $T \in A(V)$ is singular iff there exists a $v \neq 0$ in V such that $vT = 0$.

Proof:

Suppose $T \in A(V)$ is singular, then there exists $S \neq 0$ in $A(V)$ such that $ST = TS = 0$.

Since $S \neq 0$.

Then there exists $w \in V$ such that $wS \neq 0$ in V .

$$\text{Let } v = wS$$

$$\Rightarrow v \neq 0 \text{ in } V.$$

$$\text{Now, } vT = (wS)T$$

$$= w(ST)$$

$$= w(0)$$

$$= 0.$$

$$\therefore vT = 0.$$

Hence there exists an element $v \neq 0$ in V

such that $vT = 0$.

Conversely, $vT = 0$ with $v \neq 0$.

To prove: T is singular

Suppose T is not singular.

(i) T is invertible, then there exists $S \in A(V)$

such that $ST = TS = I$.

Here $vT = 0$.

not regular

$$\Rightarrow (v^T)S = 0S$$

$$\Rightarrow (v^T) v(Ts) = 0.$$

$$\Rightarrow v \cdot 1 = 0, \text{ (ie) } v = 0.$$

which is a contradiction to our assumption $v \neq 0$.

$\therefore T$ is singular.

Defn: If $T \in A(V)$ then the range of T is denoted by VT and is defined by $VT = \{v^T / v \in V\}$

Note:

(i) Range of T is a subspace of V .

(ii) Range of T is all of V iff T is onto.

Theorem: 6.1.4

If V is finite dimensional over F , then $T \in A(V)$ is regular iff T maps V onto V .

Proof:

Assume T is regular.

Then there exists $T^{-1} \in A(V)$ such that $TT^{-1} = T^{-1}T = I$.

Let $v \in V$.

$$\text{Now, } v = v \cdot 1 \\ = v(T^{-1}T)$$

$$= (vT^{-1})T \in VT.$$

$$\text{Also } VT \subseteq V$$

$$VT = V.$$

By Note, T is onto. [Range of T is all of V iff T is onto]

Conversely, Assume T is onto.

To prove: T is regular.

Suppose not, T is singular.

By Theorem: 6.1.3, there exists $v_1 \neq 0$ in V such

Since $v_1 \neq 0$.

Then by Lemma 4.2.5, we can find v_2, v_3, \dots, v_n

Such that v_1, v_2, \dots, v_n form a basis of V .

Then every element in VT is a linear combination of $w_1 = v_1T, w_2 = v_2T, \dots, w_n = v_nT$.

Here $w_1 = 0$, VT is spanned by $n-1$ elements w_2, w_3, \dots, w_n .

$$\dim VT \leq n-1 < n = \dim V.$$

$\Rightarrow VT$ and V are not equal.

$\therefore T$ is not onto.

V which is a contradiction.

Hence T is regular.

Note!

An element $T \in A(V)$ is regular iff

$$\dim(VT) = \dim V.$$

Defn:

If V is finite-dimensional over F , then the rank of T is the dimension of VT , the range of T over F .

ie) rank of $T = \dim$ of range of T .

We denote it by rank of T (or) $r(T)$.

Note:

(1) If $r(T) = \dim V$ then T is regular.

$$\text{Since } r(T) = \dim(VT)$$

$$\text{Given } r(T) = \dim V$$

$$\Rightarrow \dim(VT) = \dim V$$

$\Rightarrow T$ is regular

(2) If $r(T) = 0$ then $T = 0$.

ie) T is singular.

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Lemma: 6.1.3
If V is finite-dimensional over F , then for

$S, T \in A(V)$.

1) $r(ST) \leq r(T)$

2) $r(TS) \leq r(T)$ (and so $r(ST) \leq \min\{r(T), r(S)\}$)
(and so $r(ST) \leq \min\{r(T), r(S)\}$)

3) $r(ST) = r(TS) = r(T)$ for S regular in $A(V)$.

Proof:

1) Let $S, T \in A(V)$.

Then $V \subseteq V$

Now, $V(ST) = (VS)T \subseteq VT$

By Lemma: 4.2.6, $\dim(V(ST)) \leq \dim(VT)$

i.e) $r(ST) \leq r(T)$ — ①

2) Suppose that $r(T) = m$.

$\Rightarrow VT$ has a basis of m elements say w_1, w_2, \dots, w_m .

$\Rightarrow (VT)S$ is spanned by w_1S, w_2S, \dots, w_mS .

$\Rightarrow (VT)S$ has dimension at most m .

$\Rightarrow \dim((VT)S) \leq m$.

Now, $r(TS) = \dim(V(TS))$

$= \dim((VT)S)$

$\leq m = r(T)$

$\therefore r(TS) \leq r(T)$ — ②

From ①, ② $r(ST) \leq \min\{r(S), r(T)\}$

3) Let $S \in A(V)$ is regular.

Then by Theorem: 6.1.4, S maps V onto V .

i.e) $VS = V$.

$$\text{Now, } V(ST) = (VS)T = VT$$

$$\Rightarrow \dim(VST) = \dim(VT)$$

$$\Rightarrow r(ST) = r(T)$$

$$\text{Let } r(T) = m \Rightarrow \dim(VT) = m$$

Let w_1, w_2, \dots, w_m be a basis of VT .

Then w_1s, w_2s, \dots, w_ms spanned by $(VT)s = Vb$

claim: w_1s, w_2s, \dots, w_ms are linearly Independent.

$$\text{Let } \alpha_1(w_1s) + \alpha_2(w_2s) + \dots + \alpha_m(w_ms) = 0.$$

$$(\alpha_1 w_1)s + (\alpha_2 w_2)s + \dots + (\alpha_m w_m)s = 0.$$

$$(\alpha_1 w_1 + \alpha_2 w_2 + \dots + \alpha_m w_m)s = 0$$

Since s is ~~singular~~ ^{regular}, s^{-1} exists.

$$\Rightarrow (\alpha_1 w_1 + \alpha_2 w_2 + \dots + \alpha_m w_m)ss^{-1} = 0 \cdot s^{-1}$$

$$\alpha_1 w_1 + \alpha_2 w_2 + \dots + \alpha_m w_m = 0.$$

Since w_1, w_2, \dots, w_m are linearly independent

$$\Rightarrow \alpha_1 = \alpha_2 = \dots = \alpha_m = 0.$$

Hence w_1s, w_2s, \dots, w_ms form a basis for $V(Ts)$

$$\text{now, } r(Ts) = \dim(V(Ts)) = m = \dim(VT) = r(T)$$

$$\therefore r(ST) = r(Ts) = r(T).$$

Corollary:

If $T \in A(V)$ and if $S \in A(V)$ is regular,

$$\text{then } r(T) = r(STS^{-1})$$

Proof:

$$\text{Now, } r(STS^{-1}) = r(S(TS^{-1}))$$

$$= r((TS^{-1})S) \quad [\text{By Lemma: 6.1.3}]$$

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$$= r(T(S^{-1}S))$$

$$= r(TI)$$

$$\therefore r(STS^{-1}) = r(T)$$

Sec: 6.2 Characteristic roots.

Defn: If $T \in A(V)$ then $\lambda \in F$ is called a characteristic root (or singular) of T if $\lambda - T$ is singular.

ie) $\lambda \cdot 1 - T$ is singular. where 1 represent the unit element in $A(V)$.

Theorem: 6.2.1

The element $\lambda \in F$ is a characteristic root of $T \in A(V)$ iff for some $v \neq 0$ in V , $vT = \lambda v$

Proof:

Let $\lambda \in F$ be a characteristic root of T .

$\Rightarrow \lambda - T$ is singular.

By Theorem: 6.1.3, $\exists v \neq 0$ in V such that $v(\lambda - T) = 0$

$$\Rightarrow v(\lambda \cdot 1 - T) = 0$$

$$\Rightarrow v(\lambda \cdot 1) - v \cdot T = 0$$

$$\Rightarrow \lambda(v) - vT = 0$$

$$\Rightarrow \lambda v = vT$$

Conversely,

suppose $v \neq 0$ such that $vT = \lambda v$

$$\Rightarrow v(\lambda - T) = 0$$

Thus $\exists v \neq 0$ such that $v(\lambda - T) = 0$.

By Theorem: 6.1.3, $\lambda - T$ is singular.

$\therefore \lambda$ is a characteristic root of T .

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Lemma: 6.2.1

If $\lambda \in F$ is a characteristic root of $T \in A(V)$,
then for any polynomial $q(x) \in F[x]$, $q(\lambda)$ is a
characteristic root of $q(T)$.

Proof:

Suppose that $\lambda \in F$ is a characteristic root of T

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By the above Theorem,

$$\exists v \neq 0 \text{ such that } vT = \lambda v.$$

$$\text{Now, } vT^2 = (vT)T$$

$$= (\lambda v)T$$

$$= \lambda(vT)$$

$$= \lambda(\lambda v)$$

$$= \lambda^2 v.$$

$$vT^3 = (vT^2)T$$

$$= (\lambda^2 v)T$$

$$= \lambda^2(vT)$$

$$= \lambda^2(\lambda v)$$

$$= \lambda^3 v$$

Continuing this way we get,

$$vT^k = \lambda^k v \quad \forall \text{ positive integer } k.$$

Let $q(x) = a_0 x^m + a_1 x^{m-1} + \dots + a_m$ where $a_i \in F$ be
polynomial in $F[x]$.

Now, for any $v \neq 0$.

$$v(q(T)) = v(a_0 T^m + a_1 T^{m-1} + \dots + a_m)$$

$$= v(a_0 T^m) + v(a_1 T^{m-1}) + \dots + v(a_m)$$

$$= a_0 (vT^m) + a_1 (vT^{m-1}) + \dots + a_m v$$

$$= a_0 (\lambda^m v) + a_1 (\lambda^{m-1} v) + \dots + a_m v$$

$$= (\alpha_0 \lambda^m) v + (\alpha_1 \lambda^{m-1}) v + \dots + \alpha_m v$$

$$= (\alpha_0 \lambda^m + \alpha_1 \lambda^{m-1} + \dots + \alpha_m) v$$

$$= q(\lambda) v$$

By Theorem: 6.2.1, The element $\lambda \in F$ is a characteristic root of $T \in A(V)$ iff for some $v \neq 0$ in V , $vT = \lambda v$.
 $q(\lambda)$ is a characteristic root of $q(T)$.

Theorem: 6.2.2

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If $\lambda \in F$ is a characteristic root of $T \in A(V)$, then λ is a root of the minimal polynomial of T . In particular, T only has a finite no. of characteristic root in F .

Proof:

Let λ be a characteristic root of T and $p(x)$ be a minimal polynomial over F of T .

$$\text{Then } p(T) = 0.$$

Since λ is a characteristic root of T .

By Theorem: 6.2.1, The element $\lambda \in F$ is a ch root of $T \in A(V)$ iff for some $v \neq 0$ in V , $vT = \lambda v$.
 $\exists v \neq 0$ in V such that $vT = \lambda v$.

By Lemma: 6.2.1,

$p(\lambda)$ is a characteristic root of $p(T)$.

$$\text{i.e.) } v(p(T)) = p(\lambda) v$$

$$\Rightarrow p(\lambda) v = 0 \quad (\because p(T) = 0)$$

$$\Rightarrow p(\lambda) = 0 \quad (\because v \neq 0)$$

$\therefore \lambda$ is a root of $p(x)$.

Since $\deg p(x) \leq n^2$ where $n = \dim_F V$ [By Theorem: 6.1.1]

$\Rightarrow p(x)$ has at most n^2 roots.

These finite no. of roots are also finite
no. of characteristic root of T in F .

Lemma: 6.2.2

If $T, S \in A(V)$ and if S is regular, then
 T and STS^{-1} have the same minimal polynomial.

Proof:

Let $T, S \in A(V)$ such that S is regular.

Let $P(x) = \alpha_0 + \alpha_1 x + \dots + \alpha_m x^m$ be a minimal
polynomial for T .

$$\Rightarrow P(T) = 0$$

$$\Rightarrow \alpha_0 + \alpha_1 T + \dots + \alpha_m T^m = 0$$

Now,

$$(STS^{-1})^2 = (STS^{-1})(STS^{-1})$$

$$= ST(S^{-1}S)TS^{-1}$$

$$= ST^2S^{-1}$$

$$\text{Similarly, } (STS^{-1})^3 = (STS^{-1})^2(STS^{-1})$$

$$= (ST^2S^{-1})(STS^{-1})$$

$$= ST^2(S^{-1}S)TS^{-1}$$

$$= ST^3S^{-1}$$

Continuing like this way we get,

$$(STS^{-1})^n = ST^nS^{-1}$$

$$P(STS^{-1}) = \alpha_0 + \alpha_1(STS^{-1}) + \alpha_2(STS^{-1})^2 + \dots + \alpha_m(STS^{-1})^m$$

$$= S\alpha_0S^{-1} + \alpha_1(STS^{-1}) + \alpha_2(ST^2S^{-1}) + \dots + \alpha_m(ST^mS^{-1})$$

$$= S\alpha_0S^{-1} + S(\alpha_1T)S^{-1} + S(\alpha_2T^2)S^{-1} + \dots + S(\alpha_mT^m)S^{-1}$$

$$= S(\alpha_0 + \alpha_1 T + \dots + \alpha_m T^m) S^{-1}$$

$$= S P(T) S^{-1}$$

$$= 0.$$

Let $q(x)$ be any other polynomial of degree $< m$

Such that $q(STS^{-1}) = 0$.

$$\Rightarrow S q(T) S^{-1} = 0.$$

$$\Rightarrow S^{-1} S q(T) S^{-1} S = 0 \quad (\because S \text{ is regular})$$

$$\Rightarrow q(T) = 0.$$

which is contradiction to $P(x)$ is minimal polynomial for T .

hence $P(x)$ is minimal polynomial for STS^{-1}

Hence T and STS^{-1} have the same minimal polynomial.

Defn: The element $v \neq 0 \in V$ is called a characteristic vector of T belonging to the characteristic root $\lambda \in F$ if $vT = \lambda v$.

Theorem: 6.2.3

If $\lambda_1, \lambda_2, \dots, \lambda_k$ in F are distinct characteristic roots of $T \in A(V)$ and if v_1, v_2, \dots, v_k are characteristic vectors of T belonging to $\lambda_1, \dots, \lambda_k$ respectively, then v_1, v_2, \dots, v_k are linearly independent over F .

Proof:

If $k=1$. Then v_1 is a characteristic vector of T belonging to characteristic root λ_1 .

Then $v_1 \neq 0$ such that $v_1 T = \lambda_1 v_1$.

Here $v_1 \neq 0$, then $\{v_1\}$ is linearly independent over F .

Suppose $k > 1$ such that $\{v_1, v_2, \dots, v_k\}$ are linearly

independent

Then $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_k v_k = 0$ where $\alpha_1, \alpha_2, \dots, \alpha_k$

and not all of them are 0.

\Rightarrow some nonzero coefficients as possible by

Suitably renumbering the vector the shortest relation is

$$\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_j v_j = 0 \quad \text{--- (1)}$$

where $\beta_1 \neq 0, \beta_2 \neq 0, \dots, \beta_j \neq 0$.

$$\Rightarrow (\beta_1 v_1 + \dots + \beta_j v_j)^T = 0$$

$$\Rightarrow \beta_1 (v_1^T) + \beta_2 (v_2^T) + \dots + \beta_j (v_j^T) = 0$$

Since v_1, v_2, \dots, v_k are characteristic vectors of T belonging to the characteristic roots $\lambda_1, \lambda_2, \dots, \lambda_k$ respectively.

Then $\lambda_i v_i = v_i T$ where $i = 1$ to k .

$$\therefore \beta_1 (\lambda_1 v_1) + \beta_2 (\lambda_2 v_2) + \dots + \beta_j (\lambda_j v_j) = 0$$

$$\lambda_1 \beta_1 v_1 + \lambda_2 \beta_2 v_2 + \dots + \lambda_j \beta_j v_j = 0 \quad \text{--- (2)}$$

$$\text{(2)} - \lambda_1 \times \text{(1)} \Rightarrow (\lambda_2 - \lambda_1) \beta_2 v_2 + \dots + (\lambda_j - \lambda_1) \beta_j v_j = 0$$

Since λ_j 's are distinct, $\lambda_i - \lambda_1 \neq 0$ for $i > 1$.

Hence $(\lambda_i - \lambda_1) \beta_i \neq 0$

which is a contradiction to (1) is shortest relation

Hence $\{v_1, v_2, \dots, v_k\}$ are linearly independent over F .

Corollary: 1

If $T \in A(V)$ and if $\dim_F V = n$ then T can have at most n distinct characteristic roots in F .

Proof:

Suppose T has m distinct characteristic roots in F

Then T has m distinct characteristic ~~roots~~ vectors.

By the above Theorem these m vectors are linearly

since $\dim_F V = n$ then $m \leq n$.

ie) the no. of characteristic roots of T is at most n .

Corollary: 2

If $T \in A(V)$ and if $\dim_F V = n$ and if T has n distinct characteristic roots in F then there is a basis of V over F which consists of characteristic vectors of T .

Proof: Let $\lambda_1, \lambda_2, \dots, \lambda_n$ be the distinct characteristic roots of T .

Let v_1, v_2, \dots, v_n be the characteristic vectors of T belonging to the characteristic root $\lambda_1, \lambda_2, \dots, \lambda_n$ respectively.

To prove: v_1, v_2, \dots, v_n be a basis of V over F .

By the above Theorem, $\{v_1, v_2, \dots, v_n\}$ are linearly independent over F .

To prove: $\{v_1, v_2, \dots, v_n\}$ span V .

Let $v \in V$, since $\dim_F V = n$ then any set of $n+1$ elements in V are linearly independent.

\Rightarrow The vectors v, v_1, v_2, \dots, v_n are linearly dependent over F .

$\Rightarrow v$ can be expressed as the linear combination of v_1, v_2, \dots, v_n .

$\Rightarrow v_1, v_2, \dots, v_n$ span V .

Hence $\{v_1, v_2, \dots, v_n\}$ form a basis of V .

Thus there is a basis of V over F which consists of characteristic vectors of T .

Sec: 6.3 Matrices

Defn: Let V be an n -dimensional vector space over F and let v_1, v_2, \dots, v_n be a basis for V over F . If $T \in \text{Lin}(V, V)$ then the matrix of T in the basis v_1, v_2, \dots, v_n defined by

$$m(T) = \begin{pmatrix} \alpha_{11} & \alpha_{12} & \dots & \alpha_{1n} \\ \alpha_{21} & \alpha_{22} & \dots & \alpha_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{n1} & \alpha_{n2} & \dots & \alpha_{nn} \end{pmatrix}$$

where $v_i T = \sum_{j=1}^n \alpha_{ij} v_j$ for $i=1, 2, \dots, n$, $\alpha_{ij} \in F$

Example:

Let F be a field and V be the set of all polynomials in x of degree $n-1$ or less over F on V . Let D be defined by

$$D(\beta_0 + \beta_1 x + \dots + \beta_{n-1} x^{n-1}) = \beta_1 + 2\beta_2 x + \dots + i\beta_i x^{i-1} + \dots + (n-1)\beta_{n-1} x^{n-2}$$

Then D is a linear transformation on V .

1) Consider the basis $1, x, x^2, \dots, x^{n-1}$

To find $m(D)$ in the basis $v_1=1, v_2=x, \dots, v_n=x^{n-1}$

Soln: Now, $v_1 D = 0 = 0v_1 + 0v_2 + \dots + 0v_n$

$$v_2 D = 1 = 1v_1 + 0v_2 + \dots + 0v_n$$

$$v_3 D = 2x = 0v_1 + 2v_2 + \dots + 0v_n$$

\vdots

$$v_n D = (n-1)x^{n-2} = 0v_1 + 0v_2 + \dots + (n-1)v_{n-1} + 0v_n$$

The matrix of D in the basis $\{1, x, x^2, \dots, x^{n-1}\}$ is

$$m(D) = \begin{pmatrix} 0 & 0 & 0 & \dots & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 2 & 0 & \dots & 0 & 0 \\ 0 & 0 & 3 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & n-1 & 0 \end{pmatrix}$$

Consider the basis $w_1 = x^{n-2}, w_2 = x^{n-3}, \dots, w_i = x^{n-i}, \dots, w_{n-1} = x, w_n = 1$

To find the matrix of these basis,

$$\text{Now, } w_1 D = (n-1)x^{n-2} = 0w_1 + (n-1)w_2 + 0w_3 + \dots + 0w_n$$

$$w_2 D = (n-2)x^{n-3} = 0w_1 + 0w_2 + (n-2)w_3 + 0w_4 + \dots + 0w_n$$

$$\vdots$$

$$w_i D = (n-i)x^{n-i-1} = 0w_1 + \dots + 0w_i + (n-i)w_{i+1} + 0w_{i+2} + \dots + 0w_n$$

$$w_{n-1} D = 1 = 0w_1 + 0w_2 + \dots + 1w_n$$

$$w_n D = 0 = 0w_1 + 0w_2 + \dots + 0w_n$$

\therefore The matrix of D in the basis $\{x^{n-1}, x^{n-2}, \dots, 1\}$ is

$$m(D) = \begin{pmatrix} 0 & (n-1) & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & (n-2) & 0 & \dots & 0 & 0 \\ 0 & 0 & 0 & (n-3) & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & \dots & 0 & 1 \\ 0 & 0 & 0 & \dots & \dots & 0 & 0 \end{pmatrix}$$

3) Consider the basis $u_1 = 1, u_2 = 1+x, u_3 = 1+x^2, \dots, u_n = 1+x^{n-1}$

Find the matrix of these basis.

Soln:

$$u_1 D = 0 = 0u_1 + 0u_2 + \dots + 0u_n$$

$$u_2 D = 1 = 1u_1 + 0u_2 + \dots + 0u_n$$

$$u_3 D = 2x = 2(u_2 - u_1) = -2u_1 + 2u_2 + 0u_3 + \dots + 0u_n$$

$$u_4 D = 3x^2 = 3(u_3 - u_1) = -3u_1 + 3u_3$$

$$= -3u_1 + 0u_2 + 3u_3 + 0u_4 + \dots + 0u_n$$

$$\vdots$$

$$u_n D = (n-1)x^{n-2} = (n-1)(u_{n-1} - u_1) = -(n-1)u_1 + (n-1)u_{n-1}$$

$$= -(n-1)u_1 + 0u_2 + 0u_3 + \dots + (n-1)u_{n-1} + 0u_n$$

The matrix of D in this basis $\{1, 1+x, 1+x^2, \dots, 1+x^{n-1}\}$

$$m(D) = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 \\ -2 & 2 & 0 & \dots & 0 & 0 \\ -3 & 0 & 3 & \dots & 0 & 0 \\ \vdots & & & & & \\ -(n-1) & 0 & 0 & \dots & (n-1) & 0 \end{pmatrix}$$

Note:

1) If $T \in A(V)$ where V is an n -dimensional vector space over F and if T has n distinct characteristic roots $\lambda_1, \lambda_2, \dots, \lambda_n$ in F then by Corollary 2 to Theorem 6.2.3 we find a basis v_1, v_2, \dots, v_n of V over F such that $v_i T = \lambda_i v_i$, $i = 1$ to n .

In this basis the matrix of T is

$$m(T) = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots & 0 & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 & 0 \\ \vdots & & & & & \\ 0 & 0 & 0 & \dots & 0 & \lambda_n \end{pmatrix}$$

2) Once a basis v_1, v_2, \dots, v_n of V is given then every linear transformation T we can associate a matrix

Conversely, having chosen a basis v_1, v_2, \dots, v_n of V over F then given matrix

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & & \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \quad \text{--- (1)}$$

, with $a_{ij} \in F$ gives rise to a linear transformation T defined on V by $v_i T = \sum_{j=1}^n a_{ij} v_j$ on this basis. Thus every possible square array serves as matrix of some linear transformation in the basis v_1, v_2, \dots, v_n .

In the matrix (1) the element a_{ij} is the intersection of the i th row and j th column.

ie) (i, j) th entry of the matrix.

If V is a n -dimensional vector space over F and v_1, v_2, \dots, v_n is a basis of V over F and S, T are linear transformations on V over F having matrices $m(S) = (\sigma_{ij})$ and $m(T) = (\tau_{ij})$ respectively in the given basis then

- i) $m(S) = m(T)$ iff $\sigma_{ij} = \tau_{ij}$
- ii) $m(S+T) = \lambda_{ij}$ where $\lambda_{ij} = \sigma_{ij} + \tau_{ij}$
- iii) $m(\lambda S) = \mu_{ij}$ where $\mu_{ij} = \lambda \sigma_{ij}$
- iv) $m(ST) = \varphi_{ij}$ where $\varphi_{ij} = \sum_{k=1}^n \sigma_{ik} \tau_{kj}$

Note:

- 1) $m(S+T) = m(S) + m(T)$
- 2) $m(\lambda S) = \lambda m(S)$
- 3) $m(ST) = m(S) m(T)$

Example:

If $m(S) = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ and $m(T) = \begin{pmatrix} -1 & 0 \\ 2 & 3 \end{pmatrix}$ then find $m(ST) = ?$

Here $\sigma_{11} = 1, \sigma_{12} = 2, \sigma_{21} = 3, \sigma_{22} = 4$ and

$\tau_{11} = -1, \tau_{12} = 0, \tau_{21} = 2, \tau_{22} = 3$.

using (iv), $\varphi_{11} = \sum_{k=1}^2 \sigma_{1k} \tau_{k1} = \sigma_{11} \tau_{11} + \sigma_{12} \tau_{21}$

$$= (1)(-1) + (2)(2) = 3.$$

Similarly, $\varphi_{12} = \sum_{k=1}^2 \sigma_{1k} \tau_{k2} = \sigma_{11} \tau_{12} + \sigma_{12} \tau_{22}$

$$= (1)(0) + (2)(3) = 6.$$

$\varphi_{21} = \sum_{k=1}^2 \sigma_{2k} \tau_{k1} = \sigma_{21} \tau_{11} + \sigma_{22} \tau_{21}$

$$= (3)(-1) + (4)(2) = -3 + 8 = 5.$$

$\varphi_{22} = \sum_{k=1}^2 \sigma_{2k} \tau_{k2} = \sigma_{21} \tau_{12} + \sigma_{22} \tau_{22}$

$$= (3)(0) + (4)(3) = 12.$$

$$\therefore m(ST) = \begin{pmatrix} 3 & 6 \\ 5 & 12 \end{pmatrix}$$

$$\begin{aligned} \therefore m(S) \cdot m(T) &= \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} -3+8 & 0+6 \\ -3+12 & 0+12 \end{pmatrix} \\ &= \begin{pmatrix} 5 & 6 \\ 9 & 12 \end{pmatrix} \end{aligned}$$

$$\therefore m(ST) = m(S) \cdot m(T)$$

Note: Let F_n = set of all $n \times n$ matrix whose entries are

$$= \left\{ \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \mid a_{ij} \in F \right\}$$

$$= \{ (a_{ij}) \mid a_{ij} \in F \}$$

By note, $\mathcal{I}_n \in F_n$.

$$i) (a_{ij}) = (b_{ij}) \text{ iff } a_{ij} = b_{ij} \quad \forall i \text{ and } j$$

$$ii) (a_{ij}) + (b_{ij}) = (c_{ij}) \text{ where } c_{ij} = a_{ij} + b_{ij} \quad \forall i \text{ and } j$$

$$iii) \varphi(a_{ij}) = (c_{ij}) \text{ where } c_{ij} = \varphi a_{ij} \quad \forall i \text{ and } j$$

$$iv) (a_{ij})(b_{ij}) = (c_{ij}) \text{ where } c_{ij} = \sum_{k=1}^n a_{ik} b_{kj} \quad \forall i \text{ and } j$$

Theorem: 6.3.1

The set of all $n \times n$ matrices over F form an associative algebra, F_n , over F . Then $A(V)$ and F_n are isomorphic as algebra over F if V is an n -dimensional vector space over F , then $A(V)$ and F_n are isomorphic as algebras over F . Given any basis v_1, \dots, v_n of V over F , if for $T \in A(V)$, $m(T)$ is the matrix of T in the basis v_1, \dots, v_n , the mapping $T \rightarrow m(T)$ provides an algebra isomorphism of $A(V)$ onto F_n .

Proof: Let $F_n = \{ (a_{ij}) \mid a_{ij} \in F \}$ be the set of all $n \times n$ matrices over F .

In F_n , define addition, scalar multiplication and also multiplication are given by.

$$(\alpha_{ij}) + (\beta_{ij}) = (\lambda_{ij}) \text{ where } \lambda_{ij} = \alpha_{ij} + \beta_{ij}$$

$$\lambda(\alpha_{ij}) = (\mu_{ij}) \text{ where } \mu_{ij} = \lambda\alpha_{ij}$$

$$(\alpha_{ij})(\beta_{ij}) = (\gamma_{ij}) \text{ where } \gamma_{ij} = \sum_{k=1}^n \alpha_{ik} \beta_{kj}$$

To prove: F_n is associative algebra

It is an abelian group under "+"

Define $\psi: A(V) \rightarrow F_n$ by $\psi(T) = m(T)$ the matrix of T in the basis v_1, v_2, \dots, v_n .

$$\begin{aligned} \text{Now, } \psi(S+T) &= m(S+T) \\ &= m(S) + m(T) \\ &= \psi(S) + \psi(T) \end{aligned}$$

$$\begin{aligned} \psi(\lambda S) &= m(\lambda S) \\ &= \lambda m(S) \\ &= \lambda \psi(S) \end{aligned}$$

$$\begin{aligned} \psi(ST) &= m(ST) \\ &= m(S) \cdot m(T) \\ &= \psi(S) \cdot \psi(T) \end{aligned}$$

To prove: ψ is 1-1

Let $S, T \in A(V)$ such that $\psi(S) = \psi(T)$

$$\Rightarrow m(S) = m(T)$$

$$\Rightarrow S = T$$

$\therefore \psi$ is 1-1

To prove: ψ is onto

Then the linear transformation $S: V \rightarrow V$

$$\text{defined by } v_i S = \sum_{j=1}^n \alpha_{ij} v_j$$

$$m(s) = (\alpha_{ij})$$

$$\text{ie) } \psi(s) = (\alpha'_{ij})$$

$\therefore \psi$ is onto.

Hence ψ is an algebra isomorphism of $A(V)$ onto F_n .

ie) $A(V) \cong F_n$ is algebra over F .

Theorem: 6.3.2

If V is n -dimensional over F and if $T \in A(V)$ has the matrix $m_1(T)$ in the basis v_1, \dots, v_n and the matrix $m_2(T)$ in the basis w_1, \dots, w_n of V over F , then there is an element $C \in F_n$ such that $m_2(T) = C m_1(T) C^{-1}$.
In fact, if S is the linear transformation of V defined by $v_i S = w_i$ for $i = 1, 2, \dots, n$, then C can be chosen to be $m_1(S)$.

Proof:

$$\text{Let } m_1(T) = (\alpha_{ij}) \text{ and } m_2(T) = (\beta_{ij})$$

$$\text{Then } v_i T = \sum_{j=1}^n \alpha_{ij} v_j \text{ and } w_i T = \sum_{j=1}^n \beta_{ij} w_j$$

Let S be the linear transformation on V defined by $v_i S = w_i$, $i = 1$ to n .

Since $\{v_1, \dots, v_n\}$ and $\{w_1, \dots, w_n\}$ are the basis of V over F . Then S maps V onto V .

$\Rightarrow S$ is invertible in $A(V)$ [By Theorem: 6.1.4]

$$\text{Now, } w_i T = \sum_{j=1}^n \beta_{ij} w_j \quad \text{--- (1)}$$

$$\text{Since } w_i = v_i S$$

Then, $(D) \Rightarrow (v_i, S) T = \sum_{j=1}^n \beta_{ij} v_j S$

$$v_i (ST) = \sum_{j=1}^n \beta_{ij} v_j S$$

Since S is invertible, S^{-1} exists.

$$\therefore v_i (ST) S^{-1} = \sum_{j=1}^n \beta_{ij} v_j S S^{-1}$$

$$v_i (STS^{-1}) = \sum_{j=1}^n \beta_{ij} v_j$$

$$\therefore m_1(STS^{-1}) = (\beta_{ij}) = m_2(T)$$

We know that, $T \rightarrow m_1(T)$ is an isomorphism of $A(V)$ onto F_n .

$$\begin{aligned} \text{we have } m_1(STS^{-1}) &= m_1(S) m_1(T) m_1(S^{-1}) \\ &= m_1(S) m_1(T) (m_1(S))^{-1} \end{aligned}$$

$$\text{Take } C = m_1(S)$$

$$\text{Hence } m_1(STS^{-1}) = C m_1(T) C^{-1}$$

Example:

Let V be the vector space of polynomial over F of degree ≤ 3 . Let D be the differentiation operator defined by $(\alpha_0 + \alpha_1 x + \alpha_2 x^2 + \alpha_3 x^3) D = \alpha_1 + 2\alpha_2 x + 3\alpha_3 x^2$.

Consider the basis $v_1 = 1, v_2 = x, v_3 = x^2, v_4 = x^3$

To find: $m_1(D)$ is

$$\text{Now, } v_1 D = 0 = 0v_1 + 0v_2 + 0v_3 + 0v_4$$

$$v_2 D = 1 = 1 \cdot v_1 + 0v_2 + 0v_3 + 0v_4$$

$$v_3 D = 2x = 0v_1 + 2v_2 + 0v_3 + 0v_4$$

$$v_4 D = 3x^2 = 0v_1 + 0v_2 + 3v_3 + 0v_4$$

$$\therefore m_1(D) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \end{pmatrix}$$

Consider the basis $u_1 = 1, u_2 = 1+x, u_3 = 1+x^2, u_4 = 1+x^3$.

$$\text{Now, } u_1 D = 0 = 0u_1 + 0u_2 + 0u_3 + 0u_4.$$

$$u_2 D = 1 = 1u_1 + 0u_2 + 0u_3 + 0u_4$$

$$u_3 D = 2x = 2(u_2 - u_1) = -2u_1 + 2u_2 + 0u_3 + 0u_4.$$

$$u_4 D = 3x^2 = -3(u_3 - u_1) = -3u_1 + 0u_2 + 3u_3 + 0u_4$$

$$\therefore m_2(D) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ -2 & 2 & 0 & 0 \\ -3 & 0 & 3 & 0 \end{pmatrix}$$

Let S be the linear transformation of V defined

$$\text{by } v_i S = u_i \quad \forall i = 1, 2, 3, 4.$$

$$\text{Then } v_1 S = u_1 = 1 = v_1$$

$$v_2 S = u_2 = 1+x = v_1 + v_2$$

$$v_3 S = u_3 = 1+x^2 = v_1 + v_3.$$

$$v_4 S = u_4 = 1+x^3 = v_1 + v_4.$$

\therefore The matrix of S in the basis v_1, v_2, v_3, v_4 is

$$m_1(S) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}$$

Take $C = m_1(S)$

$$C^{-1} = \frac{1}{|C|} \text{adj } C.$$

$$|C| = \begin{vmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{vmatrix} = 1 \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$|C| = 1(1-0) = 1.$$

$$\text{Cofactor of } a_{11} = + \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1.$$

$$\text{Cofactor of } a_{12} = - \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{vmatrix} = -1$$

$$\text{Cofactor of } a_{13} = + \begin{vmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1(0-0) - 1(1-0) = -1$$

$$\text{Cofactor of } a_{14} = - \begin{vmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{vmatrix} = -[1(0-0) - 1(0-1)] = -1$$

$$\text{Cofactor of } a_{21} = - \begin{vmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 0.$$

$$\text{Cofactor of } a_{22} = + \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1(1-0) = 1.$$

$$\text{Cofactor of } a_{23} = - \begin{vmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 1 \end{vmatrix} = -[1(0-0)] = 0$$

$$\text{Cofactor of } a_{24} = + \begin{vmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{vmatrix} = 1(0-0) = 0.$$

$$\text{Cofactor of } a_{31} = \begin{vmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 0.$$

$$\text{Cofactor of } a_{32} = - \begin{vmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1(0-0) = 0.$$

$$\text{Cofactor of } a_{33} = + \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1(1-0) + 0 = 1.$$

$$\text{Cofactor of } a_{34} = - \begin{vmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{vmatrix} = 1(0-0) = 0.$$

$$\text{Cofactor of } a_{41} = - \begin{vmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = 0.$$

$$\text{Cofactor of } a_{42} = + \begin{vmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{vmatrix} = 1(0-0) = 0.$$

$$\text{Cofactor of } a_{43} = - \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{vmatrix} = 1(0-0) = 0.$$

$$\text{Cofactor of } a_{44} = + \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 1(1-0) = 1.$$

$$\text{adj } C = \begin{pmatrix} 1 & -1 & -1 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}^T$$

$$C^{-1} = \frac{1}{1} \begin{pmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{pmatrix}$$

$$c^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{pmatrix}$$

Now,

$$C.M.(D) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \end{pmatrix}$$

$$C.M.(D)c^{-1} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ -2 & 2 & 0 & 0 \\ -3 & 0 & 3 & 0 \end{pmatrix}$$

$$= m_2(D)$$

$$\therefore C.M.(D)c^{-1} = m_2(D)$$